

# ERF2026 Late breaking results poster session schedule

Date: Tuesday, 24 March

Location: Forum Deli, Forum Expo

## Dear LBR presenters:

1. Please display your poster in the Forum Deli before each poster session (5-10 minutes before)
2. LBR poster session
  - Session I (Paper ID 85 - 97): **10:30 -11:10**
  - Session II (Paper ID 98 -108): **15:20 -16:00**
3. Take down the poster after the session

(Please prepare your poster before the ERF, no printing service provided on site.)

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Session I (Paper ID 85 - 97): **10:30 -11:10** (during coffee break)

| Paper ID | Paper Title   | Primary Contact Author Name |
|----------|---|-----------------------------|
| 85       | Towards Developing Standards and Guidelines for Robot Grasping and Manipulation Pipelines in the COMPARE Ecosystem          | Adam Norton                 |
| 87       | Evaluating robots and their safety in public spaces — standards, test pieces and examinations                               | Sven Schneider              |
| 88       | UAV approach for Indoor Warehouse Inventory Operations  | André Dias                  |
| 89       | ROBO-KNOT & INSIGHT: KNOWLEDGE TRANSFER PROJECTS TO BOOST COLLABORATION BETWEEN ACADEMIA AND INDUSTRY                       | Angel Dacal-Nieto           |
| 90       | Automatic reconfiguration of robot paths for zero defect manufacturing processes  | Daniela Kirchberger         |
| 92       | The Quest for Diversity in Human-Robot Communication  | Jennifer Renoux             |
| 93       | Multimodal User-Aware Dialogue Architecture Based on LLMs   | Alessandra Sorrentino       |
| 94       | Active vs. Passive Exoskeletons: Unlocking Sector-Specific Potential Across Work Domains                                    | Cecilia Scoccia             |
| 95       | AI-Driven Robotics for Textile Recycling: Enhancing Fiber Detection and Accessory Removal                                   | Tony Ferreira               |
| 96       | Evaluating Children Engagement and Robot Perception interacting with NAO robot in Educational Context: a Feasibility Study. | Laura Fiorini               |
| 97       | CARGO: Container-unloading Autonomous Robot Pipeline  | Manuel Fernando Dos Santos  |

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Session II (Paper ID 98 - 108): **15:20 -16:00** (during coffee break)

| Paper ID | Paper Title  | Primary Contact Author Name |
|----------|--|-----------------------------|
| 98       | Rail-type and Tethered UAV multi-robotic system for autonomous bridge visual inspection                      | Nahuel Jose                 |
| 99       | A GAN-based Socially Assistive Robot Support for Paediatric Venipuncture: Co-Design and Preliminary Findings | Elena Adelucci              |
| 100      | Imitation Learning for Human-Robot Collaborative Battery Disassembly: A Comprehensive Review                 | Cecilia Scoccia             |
| 101      | A Socially Assistive Robotic Coach for Quantitative Fugl-Meyer Assessment in Post-Stroke Rehabilitation      | Laura Fiorini               |
| 102      | Human-Robot Communication needs Deliberation!  | Kiran Sabu                  |
| 103      | Modular Multi-Robot Teleoperation System for Remote Supervision and Intervention                             | Manuel Couto                |
| 104      | XR-based Robot Teaching for Manipulation Tasks   | Marcelo Petry               |
| 105      | EuroCore - Robotics on the European AI on Demand Platform  | Uwe Kockemann               |
| 106      | Pallet and Pocket Detection is Here!   | Daniele Caldana             |
| 107      | REISAR: Multi-Sensor Robot Inspection for Sewer Tunnel Network   | Aouni Mejri                 |
| 108      | A Multi-Objective Approach to Sustainable and Human-Centric Manufacturing                                    | Fernando Castaño            |